

ATMOSPHERIC & SPACE TECHNOLOGY RESEARCH ASSOCIATES

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First Measurements of Ionospheric TEC and GPS Scintillations from an Unmanned Marine Vehicle

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Overview

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- Motivation
- Introduction
- GPS System Design

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- Results
- Summary



Motivation

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- Ionospheric variability can have a significant impact various RF systems, including communications, navigation, and surveillance operations.
- Lack of data from oceanic regions hinders our ability for global ionospheric specification and scintillation forecasting.
- Traditional ground-based ionospheric monitoring systems have not permitted coverage of large ocean areas or on-demand theater coverage.



- Technology Need
 - Inexpensive, lightweight, low-power,

and robust ionospheric monitoring system that can fill data gaps in coverage.

GAMMA GPS Field Tests

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- Successful field tests in Hawaii (2013, 2014) and Peru (2015)
- Fully-processed real-time ionospheric TEC and scintillation parameters

GAMMA Software GPS Rx

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- A software GPS Rx has been designed to provide continuous ionospheric TEC and scintillation from oceanic region
- The receiver has the following capabilities:
 - Tracks GPS L1 and L2C signals even through deep fades
 - Pseudorange-based TEC
 - > Carrier phase delta TEC
 - > Operates at low power (~4.5 W)
 - > Monitors and reports on its state of health
 - Compensates for buoy motion on scintillation measurements
 - Fully reconfigurable including data-rates,
 PLL and DLL bandwidths, etc.



GAMMA GPS showing the RF Front End (top), onboard computer (middle), and the DSP (bottom).

Motion Causes Artificial Sigma-Phi



• GPS measurements of ionospheric TEC and scintillation from moving platforms, such as ocean buoys, are extremely challenging

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- Motion creates large phase variations that look like phase scintillation
- Creates a significant problem when attempting to measure real scintillation from a moving platform
- PLL bandwidth of standard GPS receivers too narrow to maintain satellite lock
- Current GPS phase scintillation techniques cannot discriminate between antenna motion and ionospheric irregularities



GPS Acquisition Strategy

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- EML chip spacing = 0.1
- PLL bandwidth = 7.5 Hz
- DLL bandwidth = 0.1 Hz

- EML chip spacing = 0.1
- PLL bandwidth = 40 Hz
- DLL bandwidth = 0.05 Hz



Solution:

- Use the integrated carrier phase to calculate antenna motion over the scintillation window
- Use this information to remove the effect from the integrated carrier phase
- Re-calculate sigma phi using corrected integrated carrier phase







ROTI

Validation in Peru

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- January 21, 2015.
- Wave Glider deployed 11 miles off the coast of Lima.
- Scintillation event recorded by GAMMA from 0300 to 0400 UT on Jan 21 coincides well with the σ_{ϕ} increase measured by the ground-based GAMMA receiver in Lima at the same time.



*Science VTEC from the Wave Glider (Hawaii) Technology * Appl

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Land Based Measurement: Mauna Kea CORS GPS (25 miles from the Wave Glider)

GAMMA GPS receiver on the ocean





- January 21, 2015.
- GAMMA on Wave Glider in good agreement with GAMMA in Lima, Peru



Summary

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- Existing GPS receivers are not able to provide ionospheric TEC and scintillation measurements from mobile platforms
 - Requirements for different PLL and DLL bandwidths than usually used on static systems
- We have developed a software GPS receiver with the capability to dynamically change receiver bandwidths based on the sea state
- New algorithm to calculate phase scintillation and remove antenna motion
- 3 successful field tests (Hawaii and Peru)
- Multi-day tests supported by ground instrumentation
- Validated TEC and phase scintillations measurements from ground GPS receivers
- Upcoming field tests in May and June (Hawaii and Australia)

Acknowledgement

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