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REALISTIC IONOSPHERE Specification in Support of a TID Warning System



15th International Ionospheric Effects Symposium Alexandria ● Virginia ● May 9-11, 2017

Session 2a | HF Modeling, TIDs, and Geolocation

Outline

- Realistic Ionosphere Concept
- IRTAM: Assimilation Techniques for Real-Time IRI
 - GIRO (ground-based) V0.2 close to V1.0 release
 - Moving platform extension encouraging early results from ELO
- TID Explorer
 - Frequency-Angular Sounding (FAS)
 - Digisonde-to-Digisonde (D2D) sounding with HF pulses
- RayTRIX: Raytracing through Realistic Ionosphere eXplorer
 - Based on HR2006 Raytracing code.
 - Offline testing results available
- TID Warning system: transition to fully autonomous operation
 - Intelligent systems for RI



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Digisonde data courtesy of Robert Moore, Florida University

РХа Session

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Realistic lonosphere = IRTAM + TID + RayRTIX

1. IRI-based Real-Time Assimilative Model

1A. IRTAM driven by GIRO (ground-based network of ionosondes)



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Global Ionosphere Radio Observatory Real-time GIRO ionosondes, ~60 RT locations

IRTAM v0.2A

2017.01.31 01:00:00 UT

http://giro.uml.edu



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Global Ionosphere Radio Observatory Real-time GIRO ionosondes, ~60 RT locations + upcoming RT locations

IRTAM v0.2A

2017.01.31 01:00:00 UT

http://giro.uml.edu

- RT ionosonde partners
- Upcoming RT Digisonde partners
- Potential RT Digisonde partners



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May 9,

Alexandria

Session 1a

IRTAM Deviation Maps

HOW IONOSPHERE IS DIFFERENT FROM ITS QUIET-TIME STATE

IRTAM v0.1C

Time UT - 2004.11.07 15:52:00

IRTAM v0.1C

Time UT - 2004.11.07 15:52:00

Global Nowcast



Map: foF2 (IRTAM-IRI) MHz





Is this real?



100

Map: hmF2 (IRTAM-Brunini) km

IRTAM Solutions to AM Challenges

- Spatial prediction in areas of no GIRO coverage
 - Not interpolation/extrapolation of hmF2
 - Not interpolation/extrapolation of AhmF2 ("measurement model" deviations)
 - Interpolation/extrapolation of divrnal harmonics of Δ hmF2
- Diurnal harmonics of Δ are determined first
 - 24-hour previous history of Δ is evaluated at each GIRO site
- Each harmonic is expanded into its own spatial basis
- No propagation of update step to forecast step
 - Each update step is restarted with new sliding 24-hour windows



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Red spot over Africa



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Red-spot Validation

with South African measurements



RSA data excluded

RSA data courtesy of Lee-Anne McKinnel, SANSA







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24-hour Diurnal Harmonics Expansion 4DDA approach is robust to autoscaling blunders



Eglin AFB foF2 measurements courtesy USAF NEXION program

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Autoscaling Jitter Protection

셼 Fortaleza Fzaom





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foF2 (no jitter)

Fortaleza DPS4D measurements courtesy Inez Batista, INPE, Brazil



IRTAM complementary to TEC maps Slab Thickness Peak Density **Peak Density Height Total Electron Content** ΔΤΕС $\Delta N_{\rm m}$ F2 $\Delta h_{\rm m}$ F2

Deviation from expected quiet-time behavior Red: larger than model Blue: smaller than model

from Madrigal

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Substorm March 17, 2015 23:22UT

TEC maps courtesy Madrigal @ MIT Haystack Observatory; [Coster et al., 2008]



Realistic lonosphere = IRTAM + TID + RayRTIX

1. IRI-based Real-Time Assimilative Model

1B. IRTAM Extension for moving platform data (space-based sensors)



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Assimilating Data from Moving Platforms

- Occasional fly-bys
- No means to determine diurnal harmonics
- Vernier Scale of IRTAM technologies
 - Elastic Linear Optimization Method
 - Enlarging the expansion basis order/degree to capture finer detail than IRI
 - Iterative manipulation of coefficients, in groups, to accomplish the fit



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Elastic Linear Optimization (iterative)

Diurnal Expansion

$$\begin{bmatrix} F_{i}^{(T)}, i \in [0, 2I] \\ P(T, \varphi, \lambda) = F_{0}^{(T)} a_{0}(\varphi, \lambda) + \sum_{i=1}^{I} \begin{bmatrix} F_{2i-1}^{(T)} a_{2i-1}(\varphi, \lambda) \sin(iT) + F_{2i}^{(T)} a_{2i}(\varphi, \lambda) \cos(iT) \end{bmatrix}$$

Geographic (Zonal) Expansion

$$F_{j}^{(L)}, j \in [0, 2J]$$

$$P(T,\varphi,\lambda) = \mathbf{F}_{0}^{(L)}b_{0}(T,\chi) + \sum_{j=1}^{J} \left[\mathbf{F}_{2j-1}^{(L)}b_{2j-1}(T,\chi)\sin(j\varphi)\cos^{j}\lambda + \mathbf{F}_{2j}^{(L)}b_{2j}(T,\chi)\cos(j\varphi)\cos^{j}\lambda\right]$$

Geomagentic (Meridional) Expansion

$$F_{k}^{(M)}, \ k \in [0, \ K]$$

$$P(T, \varphi, \lambda) = \sum_{k=0}^{K} F_{k}^{(M)} c_{k}(T, \varphi, \lambda) \sin^{k} \chi$$

F factors are linear modifiers of the coefficients in groups, ensuring *elastic*, constrained transformation of the model

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Realistic lonosphere = IRTAM + TID + RayRTIX

2. Traveling lonospheric Disturbances:

Detection and evaluation



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TID Evaluation using D2D and FAS HF Pulsed sounding for multi-path resolution $N(z_0, t; x, y) = N_{bg}(z_0, t; x, y) \left[1 + A_N \cos\left\{\Omega t - K[x\cos\Theta + y\sin\Theta] + \Phi_0\right\}\right]$ Altitude $V_{\rm p}, \Theta$ Zn observed nferred ρ_1 ρ_2 f_{D} ε, β X Distance Rx Тx

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FAS and SAF



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2 x 1 km UTR-2 phased array



Frequency and Angular Sounding (FAS):

- 1995: initial results from the FAS team at RIAN [Beley, Galushko, Yampolsky]
- 2012: Implemented in Digisonde [Paznukhov *et al.*] for groundbased HF power beacons
- 2017: Implemented in European Net-TIDE project for D2D links [Reinisch *et al.*]
- Synthesis of Angles and Frequency (SAF):
 - 2016: Simulated variations of angles/frequency [Huang et al.]
 - Required precision of angle measurements ~1°
 - Required signal-to-noise ratio (SNR) is 30-40 dB
 - Unprecedented fidelity of Digisonde operations needed



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European Net-TIDE Project

presented earlier today in 1A session



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"EGU Opening" TID: April 21, 2017 19:00 UT

Dourbes to Roquetes link (1082 km)



Autor Ponstolic EOP along the signal path. the CO OP is matched to the Assemblation III profer at the



Alexandria , VA Session 1a | HF Mode

15% TID, 410 m/s 2500 km, 100 min 245° azimuth CW

Accuracy sufficient for a warning system

Multi-path separation at work





"EGU Opening" TID: 1700 to 2300 UT

Průhonice to Juiliusruh link (517 km) ["northern link"]



Doppler: Start: 2017-04-21 17:00:00, End: 2017-04-21 23:00:00, Radio Path: JR055 <-- PQ052, Freq: 2450, Pol: ORDINARY





Azimuth: Start: 2017-04-21 17:00:00, End: 2017-04-21 23:00:00, Radio Path: JR055 <-- PQ052, Freq: 2450, Pol: ORDINARY



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Net-TIDE warning system

TID Warning About Net-TIDE Rules of the Road



Help

Info

TID characteristics
Ref. Time: 2017-05-07T02:02:35.000Z
Ref. Loc(N,E,km): 14.0300 52.3000 221.000
Amp (%): 12.4000
Period (min): 130.000
Prop. Azim (CW): 196.100
Wavelength (km): 2000.00
Phase velocity (m/s): 256.410
Confidence (%): 0.00000
Uncertainty (%): 100.000

Link information Tx/Rx: PQ052-->JR055 Distance (km): 517.000 Bearing (CW): 170.500 Ray Path (km): 736.000 OEL Cutoff (km): 627.000 An. win (min): 0.00000





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Realistic lonosphere = IRTAM + TID + RayRTIX

3. Ray Tracing through Realistic Ionosphere eXplorer



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RayTRIX is

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- HR2006 ray tracing code with Spitzer capability for NVI cases
- Realistic lonosphere:
 IRTAM+ TID + local tilt
- Currently offline, transition to GPU in progress



Prof. Xueqin Huang 1939-2016



Outlook

- Realistic lonosphere combines IRI-based Real-Time Assimilative Model with TID Explorer detection of TID events for TID warning and HF raytracing applications
 - IRTAM is in operation since 2013
 - TID Explorer is scheduled for release in 2017
 - RayTRIX environment in early phase of testing
- IRTAM: close to completion; URSI INAG Working Group G.1 actively pursues real-time ionosonde network operation
- TID-X: RETID (USA) and Net-TIDE (Europe) projects support TID detection and evaluation using Digisonde oblique sounding data
- RayTRIX is in transfer to operations at LGDC

Acknowledgements: IARPA HFGeo, AFRL SBIR "RETID", NATO SfP 984894



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