

Feasibility Study for Reconstructing the Spatial-Temporal Structure of TIDs from High-Resolution Backscatter Ionograms

**Dr. L. J. Nickisch, Dr. Sergey Fridman, Dr.
Mark Hausman**

NorthWest Research Associates, Monterey, California

Dr. Geoffrey S. San Antonio

Naval Research Laboratory, Radar Division

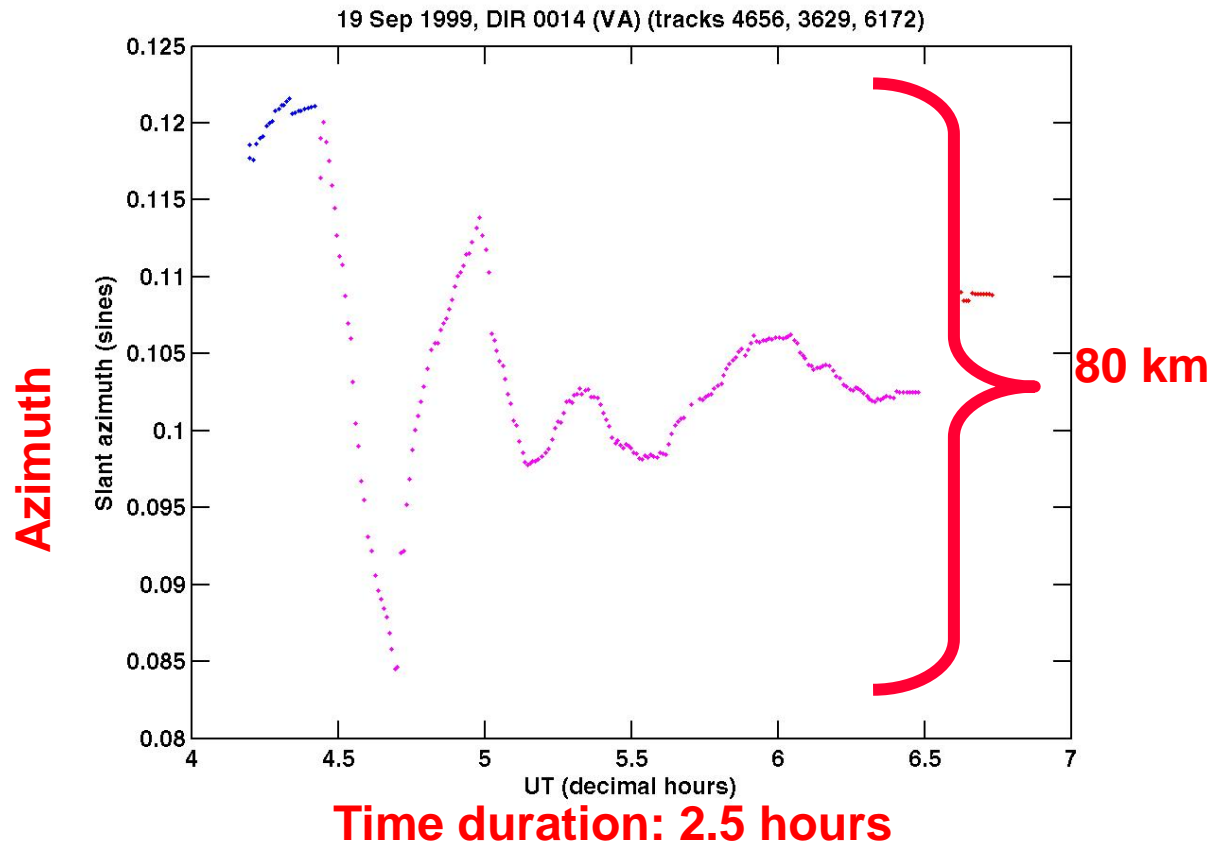
Presented at the 2015 Ionospheric Effects Symposium

12 May 2015

Motivation

- **Medium-scale TIDs can cause large geolocation errors for over-the-horizon (OTH) radar**
 - Apparent target location swings of tens of kilometers in 5-10 minutes

- **ROTHR-Virginia return from stationary transponder in Jamaica**



Motivation (cont.)

- **OTH radars routinely collect backscatter soundings**
 - **Wide Sweep Backscatter Ionogram (WSBI)**
 - **Surface clutter returns as a function of delay and transmission frequency for a span of azimuths**
- **Can information from WSBI be used to infer TID structure in real time?**

GPS Ionospheric Inversion (GPSII)

- **The algorithm can assimilate diverse TEC-related data obtained on transionospheric propagation paths**
 - **GPS L1/L2 beacon signals \Rightarrow GPSII**
 - > Dual frequency group delay data (absolute TEC)
 - > Dual frequency phase delay data (relative TEC)
 - **TEC data obtained with LEO beacons**
 - **Occultation-type oblique TEC from space-based receivers (CHAMP, COSMIC, DORIS)**
- **Other data types**
 - **Vertical/Oblique soundings (especially important for HF skywave applications)**
 - **HF backscatter soundings**
 - **On-board plasma density measurements from satellites (such as CHAMP, DMSP)**
 - **Doppler sounding data**

The Ionospheric Reconstruction Problem: Tikhonov Method

$$N(\mathbf{r}, t) = N_0(\mathbf{r}, t)e^{u(\mathbf{r}, t)}$$

$$U = \{ \{u(\mathbf{r}, t)\}, \text{Biases} \}$$

$$Y \approx M[U]$$

Y is the set of measured absolute/relative TEC values and data points from other types of ionospheric measurements.

The solution must fit the data within errors of measurements.

$$(Y - M[U])^T S^{-1} (Y - M[U]) / \dim(Y) \leq 1$$

Error covariance matrix

There are infinitely many such solutions:

The smoothest solution is selected by minimizing the stabilizing functional

$$U^T P^{-1} U \rightarrow \min$$

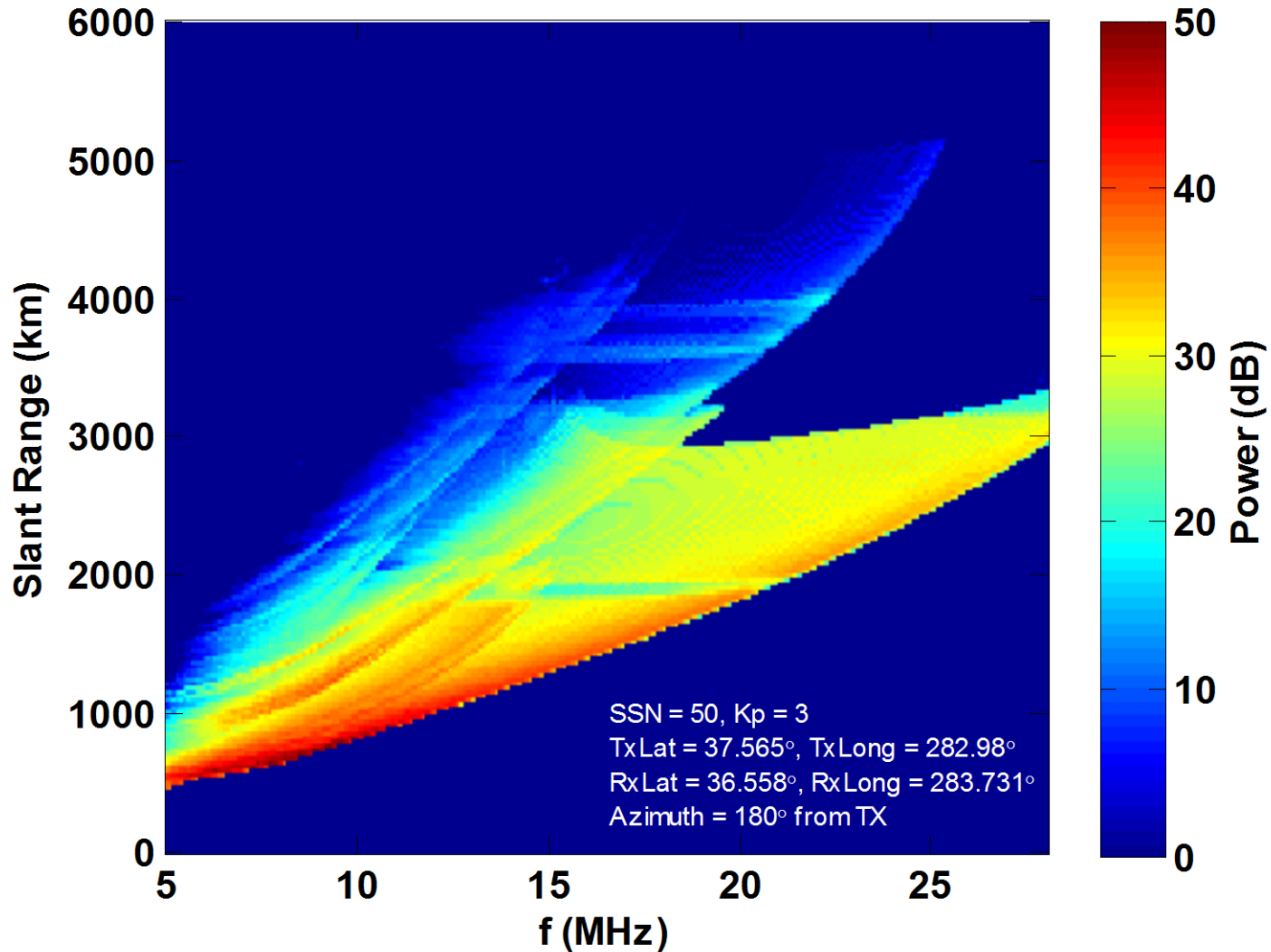
Pseudo-covariance matrix

-The pseudo-covariance P matrix is defined in such a way that the stabilizing functional tends to take on larger values for unreasonably behaving solutions (“reasonable” \Leftrightarrow “smooth”).

-The nonlinear optimization problem is solved iteratively (Newton-Kontorovich).

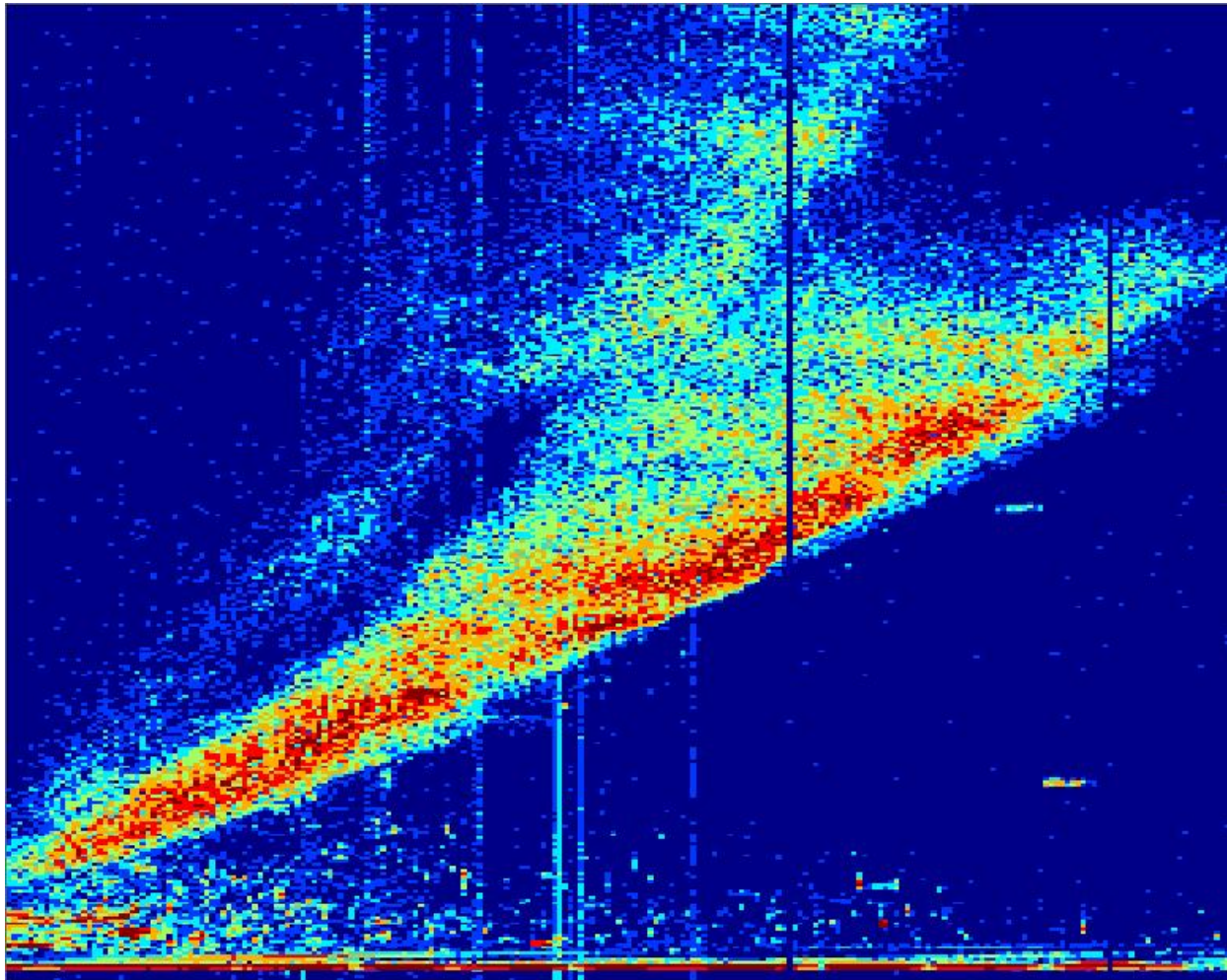
Synthetic Wide-Sweep Backscatter Ionogram

WSBI 15-Oct-2009 20:00:00 UT



Generated by NWRA HiCIRF code

Real OTHR Backscatter Ionogram



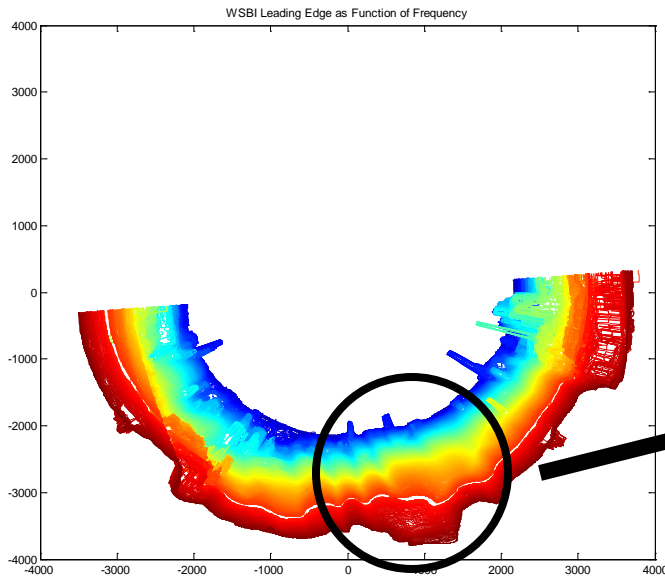
Encompasses $\sim 10^\circ$ azimuthal swath

Can WSBI leading edge structure be assimilated to expose TIDs?

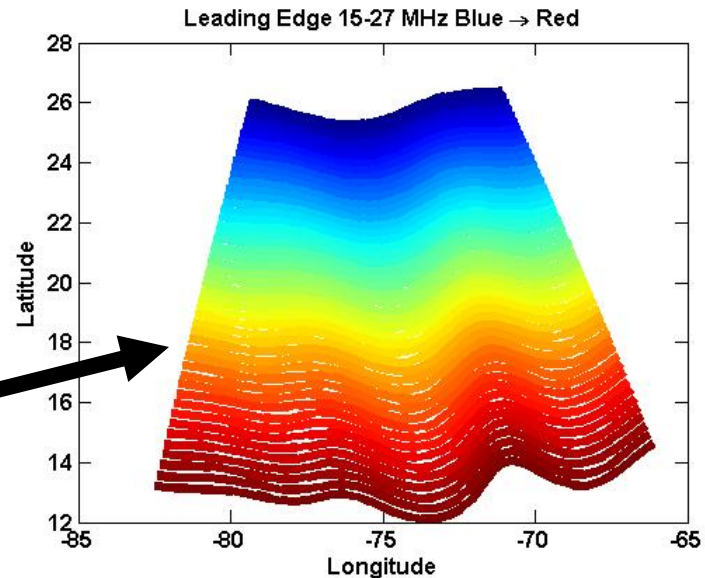
- **ROTHR WSBI**s are collected using only the end 28 elements of its 372 element receive array
 - Yields $\sim 10^\circ$ azimuthal resolution
- **Use of full aperture** would allow WSBI with $\sim 1^\circ$ spacing
 - Allows detection of leading edge TID structure
- **Assimilating WSBI leading edge data** would be an excellent way of mitigating TID effects on OTHR CR
 - WSBI are routinely collected by OTHR
 - WSBI densely sample the OTHR operational field of view
 - Modern digital technology will allow next generation OTHR to collect WSBI using the full receive aperture without impacting the surveillance mission of the radar
- **Full-aperture WSBI**s were collected on ROTHR by Dr. Geoff San Antonio (NRL) in an experimental configuration of ROTHR

High-Resolution Leading Edge Data

Color contours span 15 (blue) to 27 (red) MHz



Full aperture WSBI leading edge measurements collected by Dr. Geoffrey San Antonio (NRL)



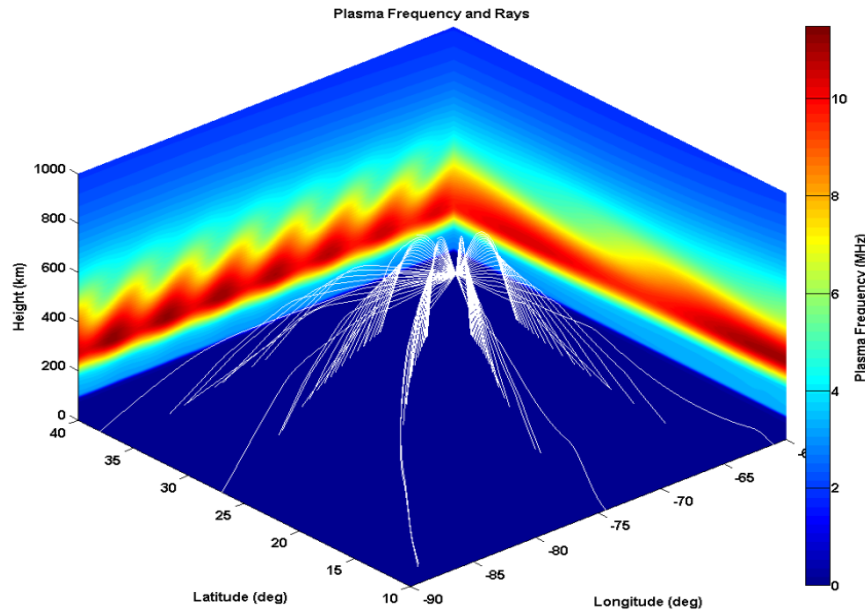
Simulated WSBI leading edges using NWRA ray tracing in TID model

The Hooke TID model was incorporated into NWRA's ray tracing code

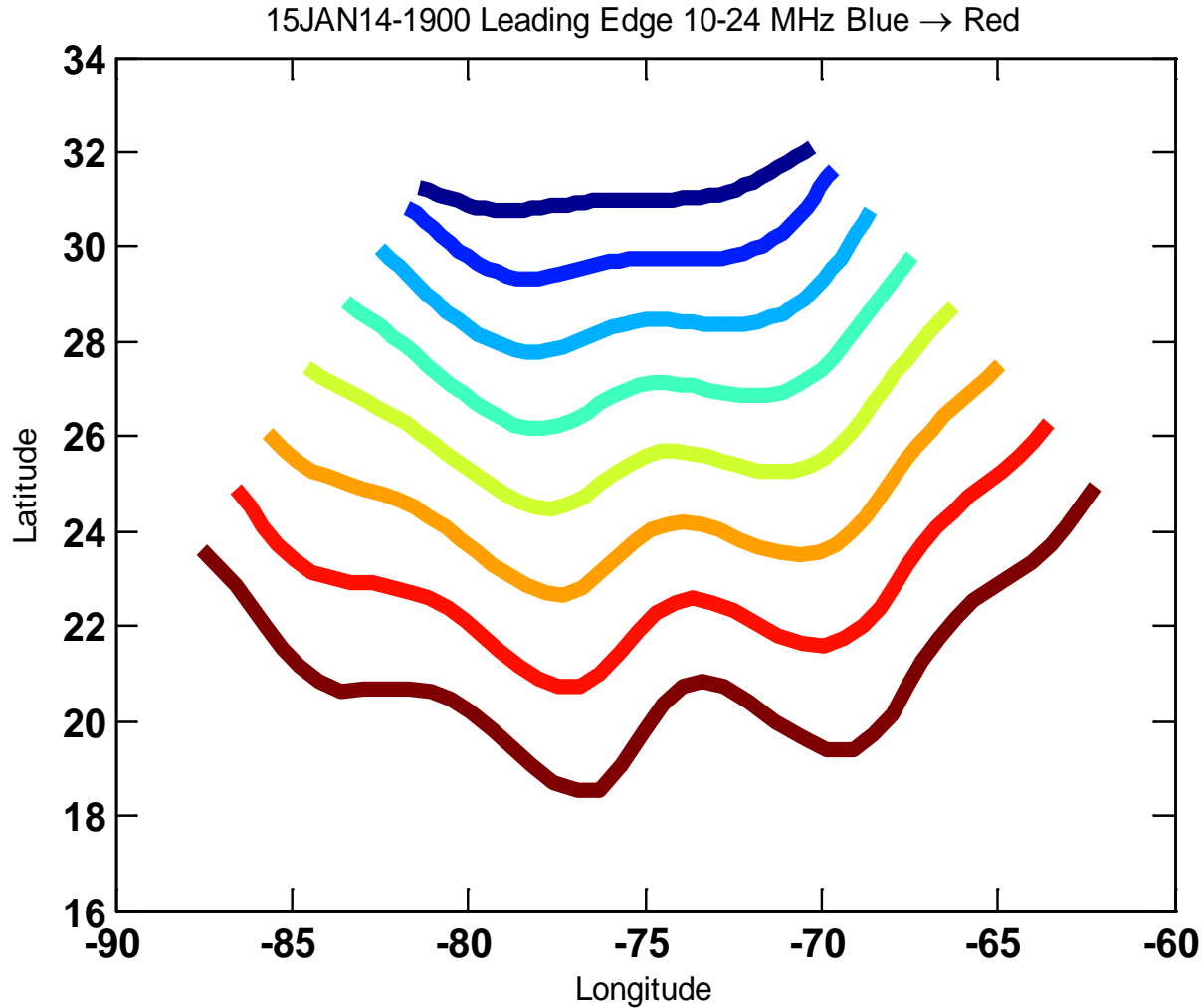
- Hooke, W. H., "Ionospheric irregularities produced by internal atmospheric gravity waves," Geophysical Monograph Series, The Upper Atmosphere in Motion, Vol. 18, pp. 780-808, 1968

$$N'_e(\mathbf{x}) = N_{e0}(\mathbf{x})U_b(z_0)\sin(I)\exp(k_{zi}(z - z_0))\omega^{-1}\sqrt{\left(\frac{\partial \ln N_{e0}}{\partial z} + k_{zi}\right)^2 + \left(\frac{k_{br}}{\sin I}\right)^2}$$

$$\exp\left\{i\left[\omega t - \mathbf{k} \cdot \mathbf{x} - \tan^{-1}\left(k_{br}/\sin I\left(\frac{\partial \ln N_{e0}}{\partial z} + k_{zi}\right)\right)\right]\right\}$$



Generated synthetic high-resolution WSBI leading edge data: Known truth data



Modified GPSII to assimilate hi-res leading edge data

$$U_n = \gamma_1 U_{n-1} + \gamma_2 U_{n-2} + v_n$$

$$\gamma_1 = 2e^{-\frac{\Delta t}{\tau}} \cos \frac{2\pi\Delta t}{T}$$

$$\gamma_1 = e^{-\frac{\Delta t}{\tau_s}} + e^{-\frac{\Delta t}{\tau_f}}$$

$$\gamma_2 = -e^{-2\frac{\Delta t}{\tau_s}}$$

$$F(x) = \sum_{\alpha=-1}^2 f_{i+\alpha} v_{\alpha} \left(\frac{x - x_i}{x_{i+1} - x_i} \right)$$

$$\gamma_2 = -e^{-\frac{\Delta t}{\tau_s} - \frac{\Delta t}{\tau_f}}$$

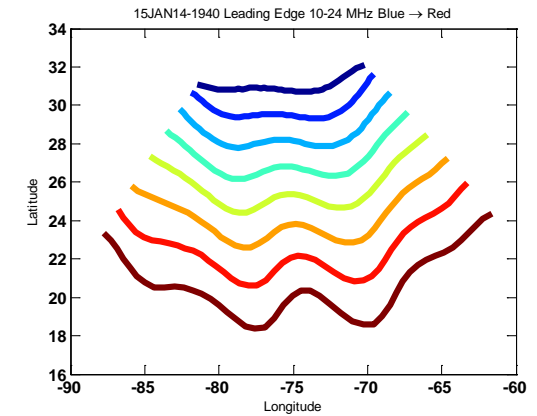
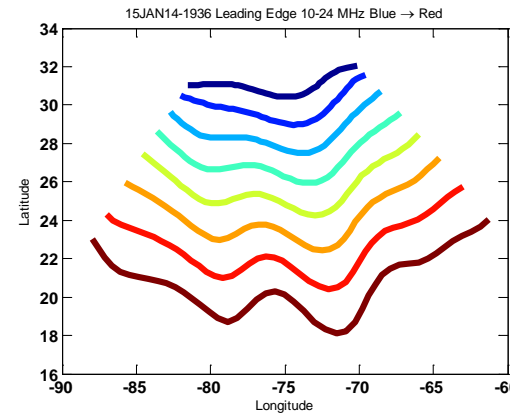
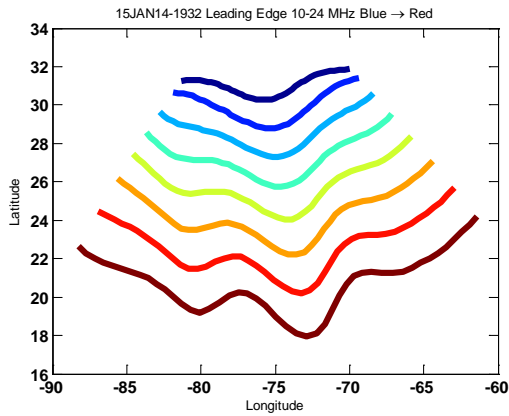
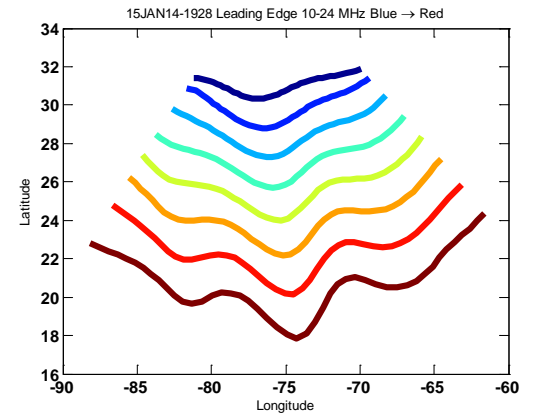
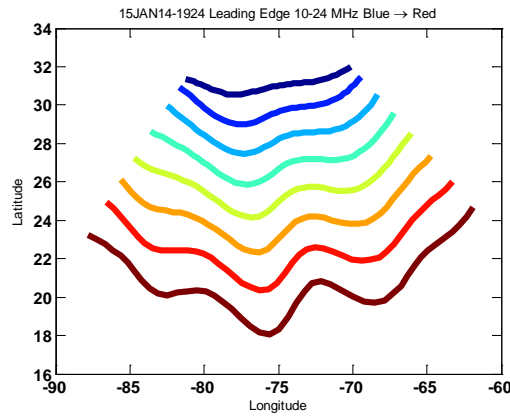
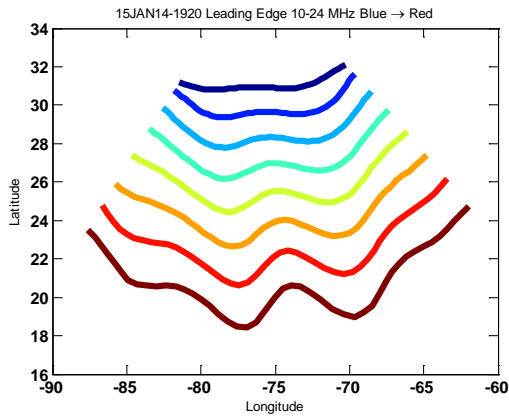
$$v_{[-1:2]}(t) = \frac{1}{2} \begin{bmatrix} -t^3 + 2t^2 - t \\ 3t^3 - 5t^2 + 2 \\ -3t^3 + 4t^2 + t \\ t^3 - t^2 \end{bmatrix}$$

$$v_{[-1:2]}(t) = \begin{bmatrix} \frac{1}{d_-(1+d_+)}(-t^3 + 2t^2 - t) \\ (2 - \frac{d_+}{1+d_+} + \frac{1-d_-}{d_-})t^3 - (3 + 2\frac{1-d_-}{d_-} - \frac{d_+}{1+d_+})t^2 + \frac{1-d_-}{d_-}t + 1 \\ (-2 + \frac{d_-}{1+d_-} + \frac{d_+-1}{d_+})t^3 + (3 - 2\frac{d_-}{1+d_-} - \frac{d_+-1}{d_+})t^2 + \frac{d_-}{1+d_-}t \\ \frac{1}{d_+(1+d_+)}(t^3 - t^2) \end{bmatrix}$$

$$F(x, y, z) = \sum_{\gamma=-1}^2 \sum_{\beta=-1}^2 \sum_{\alpha=-1}^2 f_{i+\alpha, j+\beta, k+\gamma} v_{\alpha}^x \left(\frac{x - x_i}{x_{i+1} - x_i} \right) v_{\beta}^y \left(\frac{y - y_j}{y_{j+1} - y_j} \right) v_{\gamma}^z \left(\frac{z - z_k}{z_{k+1} - z_k} \right)$$

$$x_i \leq x < x_{i+1}, y_k \leq y < y_{k+1}, z_k \leq z < z_{k+1}$$

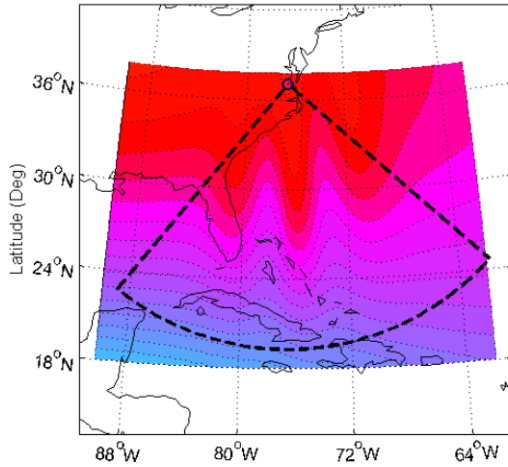
Sample Input Data



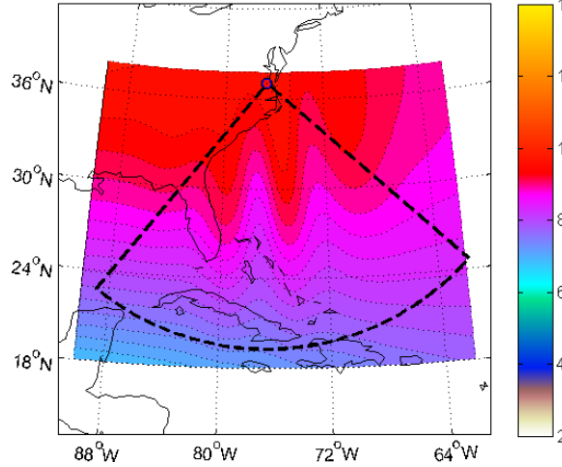
Samples separated by 4 minutes in time spanning 20 minute period of TID

Sample Output: Plasma frequency (MHz) at 250 km altitude

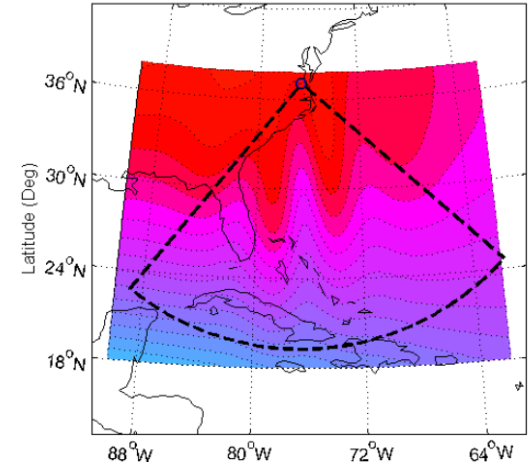
Plasma Frequency (MHz) at 250 km; 15 Jan 2014, 19:20 UT



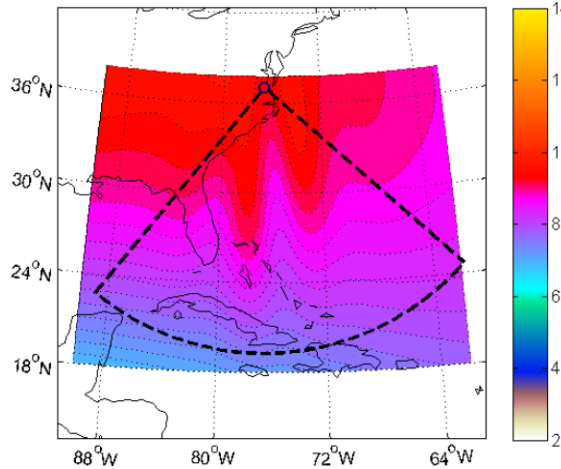
Plasma Frequency (MHz) at 250 km; 15 Jan 2014, 19:24 UT



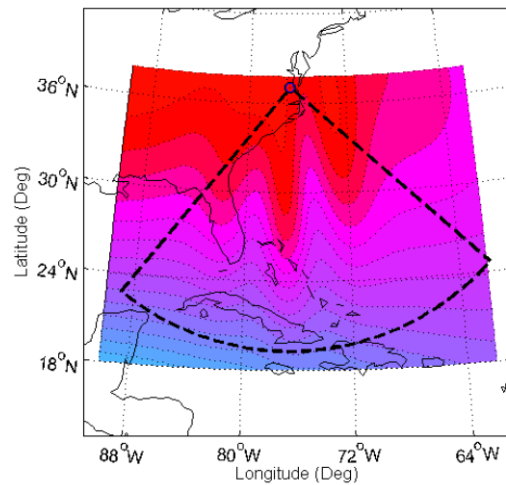
Plasma Frequency (MHz) at 250 km; 15 Jan 2014, 19:28 UT



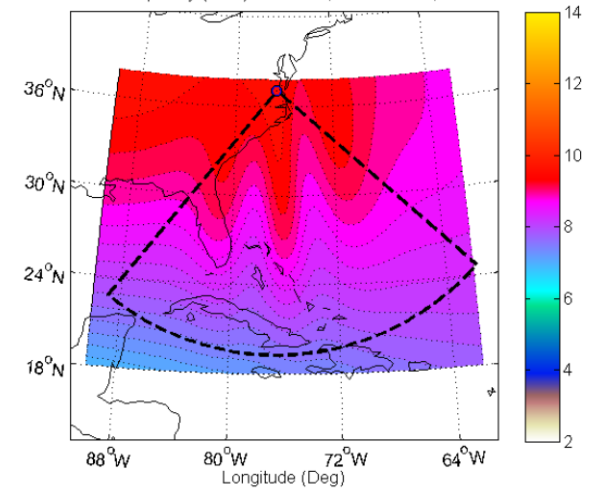
Plasma Frequency (MHz) at 250 km; 15 Jan 2014, 19:32 UT



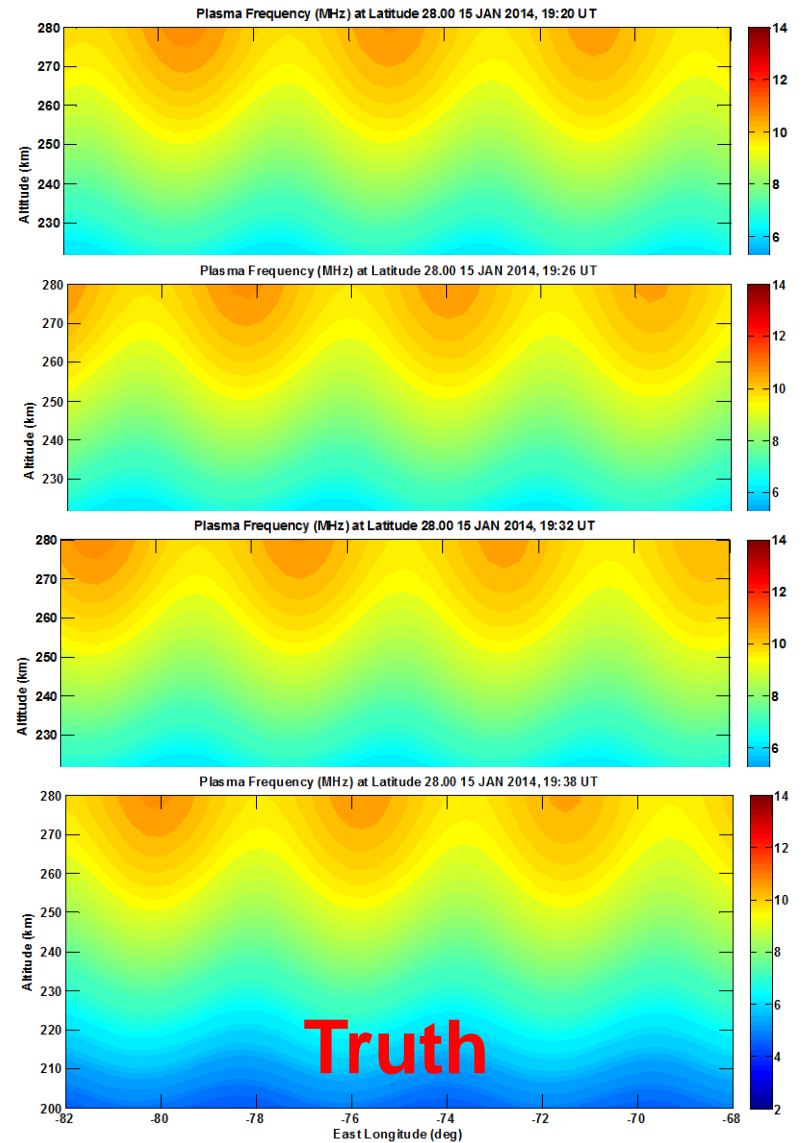
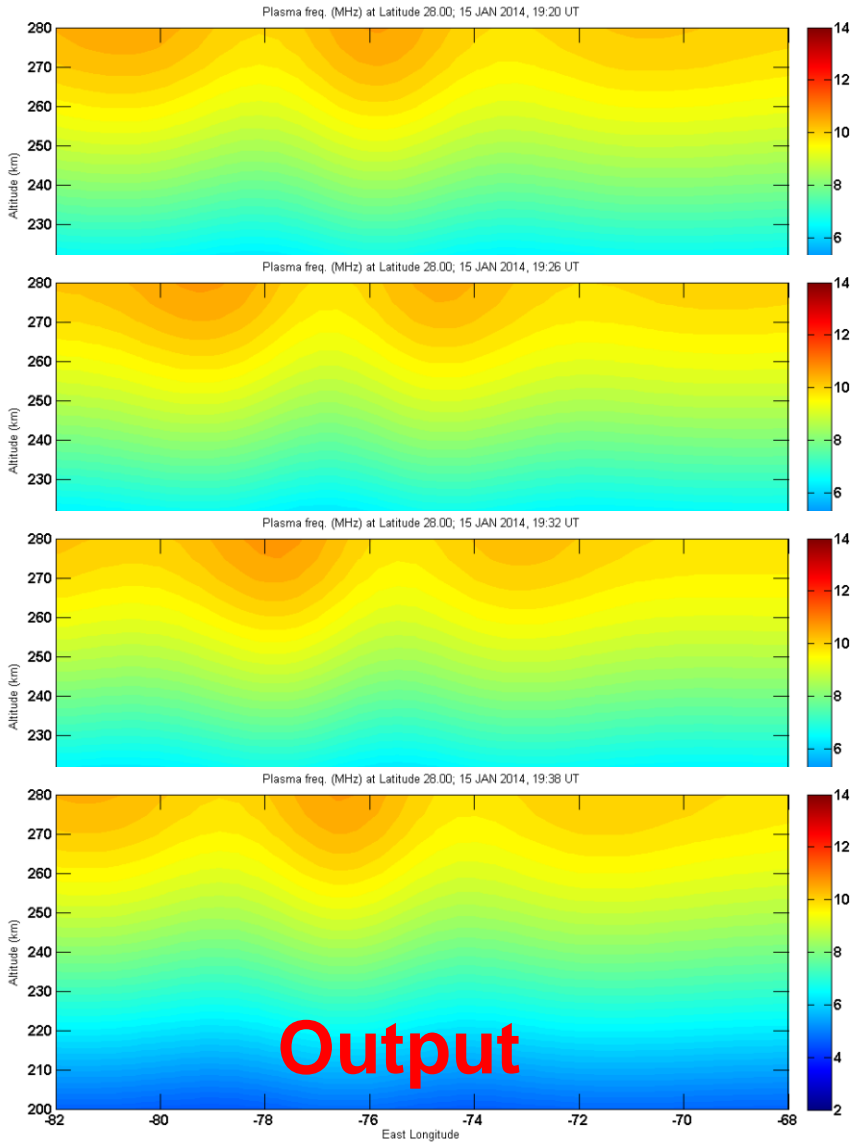
Plasma Frequency (MHz) at 250 km; 15 Jan 2014, 19:36 UT



Plasma Frequency (MHz) at 250 km; 15 Jan 2014, 19:40 UT



Comparison of Output to Truth



Future plans

- **Result of synthetic feasibility study is encouraging**
- **This work will continue over the next two years**
 - **Collect full aperture WSBI data on ROTHHR in conjunction with fixed transponder data**
 - **Add capability for assimilating surface clutter Doppler data**
 - **Field and ASTRA TIDDBIT system in the field of view of ROTHHR to collect independent TID data for comparison (Dr. Geoff Crowley)**